

There are 6 pages, 5 questions, and 100 points on this test.

- Proofs should quote results from the class to justify assertions, as in 'By the rank-nullity theorem, we can see ...'.
- If you need to use a property of a vector space or transformation or use a theorem in your answer, explain what property or theorem you are using and indicate specifically why the hypotheses of the theorem are satisfied.
- Explain your answers for each question in such a way that your reasoning can be followed!!

NOTE! Throughout this test, unless otherwise specified, assume that you are working over a field \mathbb{F} .

(20 points) 1. A matrix A is called a *rank one matrix* if the dimension of the range of A is 1.

(a) Find a 4×4 real matrix A that is a rank one matrix such that

the first row of A is $(-1 \ 2 \ 1 \ 3)$ and the first column of A is

Since A has rank 1, $\dim \mathcal{R}(A) = 1$. Since the range

of a matrix is the subspace spanned by the columns, this subspace is 1-dimensional.
In particular, every column of A is a multiple of the first column

$$\text{so } A = \begin{pmatrix} -1 & 2 & 1 & 3 \\ 3 & -6 & -3 & -9 \\ 5 & -10 & -5 & -15 \\ 1 & -2 & -1 & -3 \end{pmatrix}$$

(b) Let C be an $n \times p$ matrix over \mathbb{F} that is a rank one matrix.

Prove: If B is $m \times n$ matrix, then the matrix BC is either 0 or is also a rank one matrix.

Block the $n \times p$ matrix C by columns $C = (C_1, C_2, \dots, C_p)$

where C_j is the j^{th} column. Since C is rank 1, there is a non-zero column, call it u . Every column of C is a multiple of u ,

so $C = (a_1u \ a_2u \ \dots \ a_pu)$ where $a_1, a_2, \dots, a_p \in \mathbb{F}$ and one of these is 1. Regarding B as a 1×1 block matrix,

$$BC = B(a_1u \ a_2u \ a_3u \ \dots \ a_pu) = (a_1Bu \ a_2Bu \ a_3Bu \ \dots \ a_pBu)$$

so every column of BC is a multiple of Bu so BC is rank 1

if $Bu \neq 0$ and $BC = 0$ if $Bu = 0$

(c) In the situation of part (b) above, when is $BC = 0$?

From (b) we see $BC = 0$ if and only if $Bu = 0$,

that is $u \in N(B)$.

- (20 points) 2. Let Q be an $m \times n$ matrix over \mathbb{F} . Let P and R be invertible matrices over \mathbb{F} where P is $m \times m$ and R is $n \times n$.

- (a) Prove that the nullspace of PQ is the nullspace of Q .

Use double containment as a proof strategy.

Suppose $v \in \mathcal{N}(Q)$, so $Qv = 0$. Then $(PQ)v = P(Qv) = P \cdot 0 = 0$ and $v \in \mathcal{N}(PQ)$. Thus $\mathcal{N}(Q) \subset \mathcal{N}(PQ)$.

Let $w \in \mathcal{N}(PQ)$, so $(PQ)w = P(Qw) = 0$.

P is invertible, so this means $P^{-1}P(Qw) = P^{-1}0 = 0$ and $Qw = 0$ also. In other words $w \in \mathcal{N}(Q)$

and we see $\mathcal{N}(PQ) \subset \mathcal{N}(Q)$

Therefore $\mathcal{N}(PQ) = \mathcal{N}(Q)$.

- (b) Prove that the range of QR is the range of Q .

Suppose $x \in \mathbb{F}^m$ is in the range of QR .

Then there is y in \mathbb{F}^n so that $x = (QR)y = Q(Ry)$

Now Ry is in \mathbb{F}^n and $x = Q(Ry)$ so $x \in \text{range } Q$.

This means $\mathcal{R}(QR) \subset \mathcal{R}(Q)$.

Suppose u in \mathbb{F}^m is in $\mathcal{R}(Q)$. This means

there is w in \mathbb{F}^n so that $u = Qw$. Because R is invertible,

there is a vector z in \mathbb{F}^n so that $z = R^{-1}w$

Now $QRz = QR R^{-1}w = Qw = u$ so u is in $\mathcal{R}(QR)$

and $\mathcal{R}(Q) \subset \mathcal{R}(QR)$ and we see $\mathcal{R}(Q) = \mathcal{R}(QR)$.

- (c) Prove that $\text{rank}(PQ) = \text{rank}(Q) = \text{rank}(QR)$.

Since $\mathcal{R}(Q) = \mathcal{R}(QR)$ and the rank of a matrix is the dimension

of the ~~range~~ range, we see $\text{rank}(Q) = \text{rank}(QR)$.

Because $\mathcal{N}(PQ) = \mathcal{N}(Q)$ we see dimension $\text{dim } \mathcal{N}(PQ) = \text{dim } \mathcal{N}(Q)$.

Now the rank nullity theorem says $\dim \mathcal{N}(Q) + \text{rank}(Q) = n$

and $\dim \mathcal{N}(PQ) + \dim \mathcal{R}(PQ) = n$

and $\dim \mathcal{N}(PQ) + \dim \mathcal{R}(PQ) = n - \dim \mathcal{N}(PQ) = \text{rank}(PQ)$

Thus ~~then~~ $\text{rank}(PQ) = n - \dim \mathcal{N}(PQ) = n - \dim \mathcal{N}(Q) = \text{rank}(Q)$

so $\text{rank}(PQ) = \text{rank } Q = \text{rank } QR$.

(20 points)

3. In this question, all matrices have real number entries.

(a) Let G and H be $n \times n$ matrices such that $GH = HG$.

Let M denote the range of G and N denote the range of H .

Prove that $\mathcal{R}(GH)$, the range of GH , is a subset of $M \cap N$.

Both G and H map \mathbb{R}^n into \mathbb{R}^n . If $v \in \mathbb{R}^n$ then $Hv \in \mathbb{R}^n$ and $(GH)(v) = G(Hv)$ so $(GH)(v)$ is in $\mathcal{R}(G) = M$. Similarly $Gv \in \mathbb{R}^n$ and $(GH)(v) = (H(Gv)) = H(Gv)$ so $(GH)(v)$ is in $\mathcal{R}(H) = N$.

This shows $(GH)(v) \in M \cap N$. Since this is true for all v in \mathbb{R}^n , $\mathcal{R}(GH) \subset M \cap N$.

$$(b) \text{ Let } S = \begin{pmatrix} 2 & 1 & -1 \\ -3 & 1 & 4 \\ 1 & 3 & 2 \end{pmatrix}$$

Find a basis for the range of S acting on \mathbb{R}^3 .

Since $\mathcal{R}(S)$ is the column space of S , we know

$\mathcal{R}(S)$ is spanned by $\begin{pmatrix} 2 \\ -3 \\ 1 \end{pmatrix}$, $\begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix}$, and $\begin{pmatrix} -1 \\ 4 \\ 2 \end{pmatrix}$.

Clearly $\begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix}$ is not a multiple of $\begin{pmatrix} 2 \\ -3 \\ 1 \end{pmatrix}$, so $\begin{pmatrix} 2 \\ -3 \\ 1 \end{pmatrix}$ and $\begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix}$ are independent.

However $\begin{pmatrix} -1 \\ 4 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix} - \begin{pmatrix} 2 \\ -3 \\ 1 \end{pmatrix}$, so $\left\{ \begin{pmatrix} 2 \\ -3 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix} \right\}$ is a basis for $\mathcal{R}(S)$.

(c) For this S , find a 3×3 real matrix T so that the range of ST is NOT the range of TS and show that you are right by finding a vector in $\mathcal{R}(ST)$ that is not in $\mathcal{R}(TS)$ (or vice-versa).

Since the ideas of (a) point out that $\mathcal{R}(ST) \subset \mathcal{R}(S)$ and $\mathcal{R}(TS) \subset \mathcal{R}(T)$, if $\mathcal{R}(T)$ contains a vector not in $\mathcal{R}(S)$, $\mathcal{R}(ST) \neq \mathcal{R}(TS)$

Since (b) shows $\mathcal{R}(S)$ is a two dimensional subspace of \mathbb{R}^3 , it is easy to find a vector in \mathbb{R}^3 not in $\mathcal{R}(S)$.

For example $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ is not a linear combination of $\begin{pmatrix} 2 \\ -3 \\ 1 \end{pmatrix}$ and $\begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix}$.

$$\text{Taking } T = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix},$$

$$TS = \begin{pmatrix} 0 & 5 & 5 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \text{ and } ST = \begin{pmatrix} 2 & 0 & 0 \\ -3 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

we see $\mathcal{R}(T) = \left\{ \begin{pmatrix} r \\ 0 \\ 0 \end{pmatrix} : r \in \mathbb{R} \right\}$ So $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ is in $\mathcal{R}(ST)$ but not in $\mathcal{R}(TS) = \mathcal{R}(T)$

- (20 points) 4. For \mathcal{V} a finite dimensional vector space, a linear transformation E on \mathcal{V} that satisfies $E^2 = E$ is called a *projection on \mathcal{V}* .

Recall that in an exercise, you proved that if a linear transformation T on a finite dimensional vector space is invertible, its inverse is a polynomial in T .

Let E be a projection on the finite dimensional vector space \mathcal{V} . Show that $3E - I$ is an invertible linear transformation by finding its inverse.

The exercise shows that the inverse of $3E - I$ is a polynomial in $3E - I$.

$$\text{For example, if } p(z) = z^2 + 2z - 5 \text{ then } p(3E - I) = (3E - I)^2 + 2(3E - I) - 5I \\ = 9E^2 - 6E + I + 6E - 2I - 5I = 9E^2 - 6E + I$$

It is clear from this that, actually the inverse is a polynomial in E because every polynomial in $3E - I$ is a polynomial in E .

$$\text{Furthermore if } q(z) = a_n z^n + a_{n-1} z^{n-1} + \dots + a_2 z^2 + a_1 z + a_0 \text{ then } q(E) = a_n E^n + a_{n-1} E^{n-1} + \dots + a_2 E^2 + a_1 E + a_0 I \\ \text{But } E^2 = E, \text{ so } E^3 = E^2 \cdot E = E \cdot E = E^2 = E, \text{ etc} \\ \text{so actually } q(E) = (a_n + a_{n-1} + \dots + a_2 + a_1)E + a_0 I !!$$

These ideas suggest that to find the inverse of $3E - I$, we only need to check polynomials of the form $aE + bI$.

Suppose $aE + bI$ is the inverse of $3E - I$.

$$\text{Then } I = (aE + bI)(3E - I) = 3aE^2 + 3bE - aE - bI^2 \\ \text{This means } I = 3aE + 3bE - aE - bI = (2a + 3b)E - bI$$

We want to choose a and b real numbers so that $-b = 1$ and $2a + 3b = 0$. In other words $b = -1$ and $a = \frac{3}{2}$. Thus $(3E - I)^{-1} = (\frac{3}{2}E - I)$.

- (20 points) 5. Let \mathcal{V} be a finite dimensional vector space over the field \mathbb{F} , let T be a linear transformation on \mathcal{V} , and let v be a vector in \mathcal{V} .

(a) Let $J = \{p \in \mathbb{F}[x] : p(T)v = 0\}$. Prove that J is an ideal in $\mathbb{F}[x]$.

First we prove J is a subspace of $\mathbb{F}[x]$: Let p and q be in J and $a \in \mathbb{F}$.
 Then $(ap)(T)(v) = a p(T)v = a \cdot 0 = 0$ so $ap \in J$.
 Also $(p+q)(T)(v) = (p(T)+q(T))(v) = p(T)v + q(T)v = 0 + 0 = 0$
 and $p+q$ is in J , so J is a subspace of $\mathbb{F}[x]$.

To see J is an ideal, suppose $f \in J$ and $g \in \mathbb{F}[x]$.

Then $(fg)(T)(v) = (f(T)g(T))(v) = g(T)(f(T)v) = g(T)0 = 0$,
 $\mathbb{F}[x]$ is commutative so $fg \in J$ also, and J is an ideal.

$$(b) \text{ Let } D = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \text{ and let } v = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}.$$

Find a monic polynomial of degree 2 in the ideal $K = \{q \in \mathbb{R}[x] : q(D)v = 0\}$.

If p is a monic polynomial of degree 2, then $p(x) = x^2 - ax + b$
 where $a, b \in \mathbb{R}$.

We want $p \in K$, so we need $p(D) = D^2 - aD + bI$

$$D^2 = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix} \text{ so } p(D) = D^2 - aD + bI$$

$$\text{is } \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix} + a \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} + b \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

This means $p(D)v =$

$$\begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + a \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + b \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} 5 \\ 4 \\ 3 \end{pmatrix} + a \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} + b \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 5+3a+2b \\ 4+2a+b \\ 3+a \end{pmatrix}$$

For $p(D)v = 0$ we
 want $3a+2b = -5$
 $2a+b = -4$

so $a = -3$ and $b = 2$ works.

$$a = -3$$

Thus $p(x) = x^2 - 3x + 2$ is a monic polynomial in K .

5. (continued) Recall: $D = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}$ and let $v = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}$

and the ideal, K , is $K = \{q \in \mathbb{R}[x] : q(D)v = 0\}$.

- (c) Show that there is no monic polynomial of degree 1 in the ideal K in part (b) and explain why this means that the polynomial you found in part (b) is the monic generator of K .

Similarly, if $g(x) = x + c$, a monic polynomial of degree 1, then $g(D)v = 0$ means

$$\begin{aligned} g(x) = D + cI \quad \text{and} \quad g(D)v &= \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + b \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} + b \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 3+2b \\ 2+b \\ 1 \end{pmatrix} \neq \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \end{aligned}$$

for any b .

So there are no monic polynomials of degree 1 in J . Since we know that every ideal in $\mathbb{R}[x]$ has a monic generator, and there are no monic generators of degree 1, we know the generator has degree ≥ 2 .

Since $p(x) = x^2 - 3x + 2$ is in J , it must be a monic polynomial of lowest degree in J , that is, it must be the monic generator of J .