Application of Linear Algebra to Differential Equations

Segment 1: Introduction

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OUTLINE

- Segment 1. Introduction; the equation Y' = AY
- Segment 2. The matrix exponential
- Segment 3. Spectral Mapping Theorem for the matrix exponential
- Segment 4. Some easy examples
- Segment 5. More examples
- Segment 6. Complication: A not diagonalizable
- \bullet Segment 7. An example with A not diagonalizable

References: Section 8.3, Section 10.2

Problems: For Discussion May 1: page 328: 1, 2, 3, 4, 5 page 392: 1, 2, 4

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Solving a differential equation means finding all functions that satisfy the equation

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Solution: integrate twice to get $x(t) = -\frac{g}{2}t^2 + v_0t + x_0$ where v_0 is the initial velocity and x_0 is the initial height.

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Solution: Rewrite as
$$\frac{1}{y}\frac{dy}{dt} = a$$
 to get $\ln(y) = at + c$ or $y(t) = Ce^{at}$ where $C = e^c$

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Second derivative of unknown function y occurs, but no higher derivative, so the equation is said to be a $second\ order$ equation.

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For example, let's look at the system
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That is, the system becomes Y' = AY where $A = \begin{pmatrix} 1 & -1 \\ 2 & 4 \end{pmatrix}$

Theorem (Principle of Superposition):

If A is an $n \times n$ matrix with U and V solutions of the system Y' = AY, then for any numbers α , β , the function $W = \alpha U + \beta V$ is also a solution.

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Proof: If $W(t) = \alpha U(t) + \beta V(t)$, then $W'(t) = \alpha U'(t) + \beta V'(t)$. Since U and V are solutions of Y' = AY, we have U' = AU and V' = AV,

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so
$$\alpha U' = \alpha A U = A(\alpha U)$$
 and $\beta V' = \beta A V = A(\beta V)$. This means

$$W' = \alpha U' + \beta V' = A(\alpha U) + A(\beta V) = A(\alpha U + \beta V) = AW$$

which is the conclusion.

This is the end of the First Segment.

In the next segment, we will investigate the matrix exponential so that we can deal with the equation Y' = AY in a way analogous to the equation y' = ay.